

Abstract

A yaw rate sensor having the features of the preamble of the main claim is described. The yaw rate sensor of the present invention has force-conveying means. The central idea of the invention is that the force action conveyed by these means has a frequency such that the
5 frequency of the conveyed force action is an integral multiple of the frequency of the oscillation of the drive element parallel to the X-axis.

(Figure 4)